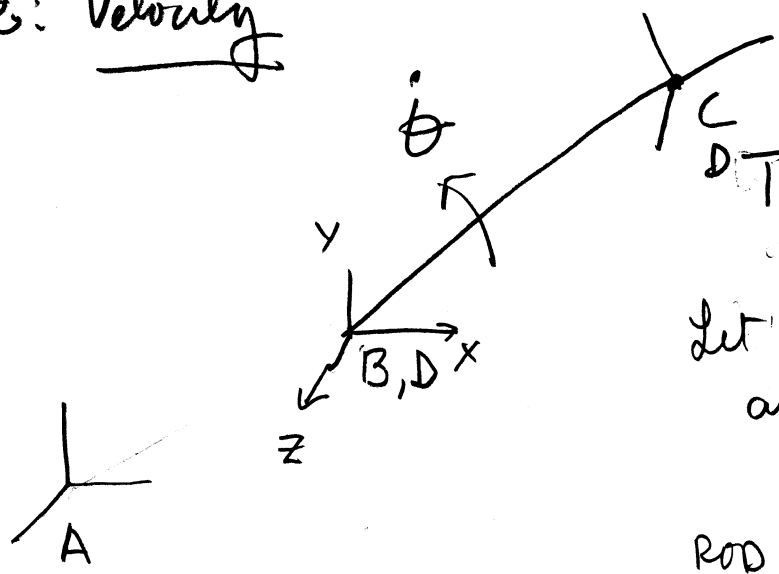


Example: Velocity



Let A, D be fixed

${}^D T_B = \text{given}$ - time varying

Let frame B + C be attached to Rod BC

ROD BC is rotating

about z_B , $\rightarrow {}^D T_B$ is not fixed.

$${}^D U_C = {}^D W_C \times {}^D P_C \Rightarrow {}^A U_C = {}^A R_D {}^D U_C$$

$$\begin{aligned} {}^A U_C &= {}^A R_D {}^D W_C \times {}^D P_C \\ &= {}^A W_C \times ({}^A P_C - {}^A P_D) \end{aligned}$$

Also

$${}^A U_C = {}^A W_B \times ({}^A P_C - {}^A P_B)$$

$$= {}^A W_B \times {}^A R_B {}^B P_C$$

$$= {}^A W_C \times {}^A R_B {}^B P_C$$

$$= {}^A W_C \times ({}^A P_C - {}^A P_B)$$

Since ${}^A W_B = {}^A W_C = {}^A z_B \dot{\theta}$ //

$$= {}^A R_D {}^D W_C$$

What if Rot BC is also translating

with ${}^A U_B$ and ${}^A W_B$ given

Two Methods to solve:

Method 1:

$${}^A U_C = {}^A U_B + {}^A R_D ({}^D W_C \times ({}^D P_C - {}^D P_D)) + {}^A W_B \times ({}^A P_C - {}^A P_D)$$

$$= {}^A U_B + {}^A R_D {}^D W_C \times {}^A R_D ({}^D P_C - {}^D P_D) + {}^A W_B \times ({}^A P_C - {}^A P_D)$$

$$= {}^A U_B + {}^A R_D {}^D W_C \times ({}^A P_C - {}^A P_D) + {}^A W_B \times ({}^A P_C - {}^A P_D)$$

$$= {}^A U_B + \underbrace{({}^A W_B + {}^A R_D {}^D W_C)}_{{}^A W_C} \times ({}^A P_C - {}^A P_D)$$

$$= {}^A U_B + {}^A W_C \times ({}^A P_C - {}^A P_D) //$$

Method 2:

$AU_C =$ motion contribution from Frame B motion
+
motion contribution from Frame C motion
with respect to B

$$= {}^A W_B \times {}^A P_C + {}^A R_D^D W_C \times ({}^A P_C - {}^A P_D)$$

$${}^A P_C = {}^A P_B + {}^A R_B^B P_C$$

$$AU_C = {}^A W_B \times ({}^A P_B + \underbrace{{}^A R_B^B P_C}_{{}^A P_C}) + {}^A R_D^D W_C \times ({}^A P_C - {}^A P_D)$$

$$= ({}^A W_B \times {}^A P_B) + {}^A W_C \times {}^A R_B^B P_C + {}^A R_D^D W_C \times ({}^A P_C - {}^A P_D)$$

$$= {}^A U_B + \underbrace{({}^A W_C + {}^A R_D^D W_C)}_{{}^A W_C} \times ({}^A P_C - {}^A P_D) //$$

note ${}^A R_B^B = {}^A P_B$